

Particle Swarm Optimization for test functions optimization

1 PSO

```
1: swarm_initialize(swarm_size)
2:  $t \leftarrow 0$ 
3: while terminal_condition not TRUE do
4:   for  $i = 1$  to swarm_size do
5:     if  $f(x_i) < f(personal\_best_i)$  then
6:        $personal\_best_i \leftarrow x_i$ 
7:     end if
8:     if  $f(personal\_best_i) < f(global\_best)$  then
9:        $global\_best \leftarrow personal\_best_i$ 
10:    end if
11:   end for
12:   for  $i = 1$  to swarm_size do
13:     for  $j = 1$  to  $d$  do
14:        $v_{i,j} \leftarrow \omega \cdot v_{i,j} + \phi_p \cdot rU(0, 1) \cdot (personal\_best_{i,j} - x_{i,j}) + \phi_g \cdot rU(0, 1) \cdot (global\_best_j - x_{i,j})$ 
15:        $x_{i,j} \leftarrow x_{i,j} + v_{i,j}$ 
16:     end for
17:   end for
18:    $t \leftarrow t + 1$ 
19: end while
20: return swarm
```

2 Algorithm description

- A particle structure:
 - x — a vector with d numbers which represents optimization function arguments - point in the domain space. \Re^n). Initialized randomly from uniform distribution and the range = *domain*.
 - v — a vector with d numbers which represents a velocity.
 - *personal_best* — the best particle posititon so far. A vector with d numbers.
 - f — fitness function (calculated from the formula e.g. Schwefel function)

domain is a given domain for a specific test function (benchmark) that will be solved by ES.

- Initial parameters

- *swarm_size* —a number of individuals in the swarm: recommended values from 10 to 50
- ϕ_p — the parameter responsible for the individuality of the particle. If the value is high, the particles are willing to follow their best locations so far $0 < \phi_p < 4$.
- ϕ_g — the parameter responsible for the social behavoir of the particle. If there is a high value, the best particle attracts the swarm $0 < \phi_g < 4$.
- ω — Inertia affects the velocity. $\omega = 1$ — particles don't slow down, $\omega < 1$ particles slow down over time, $\omega > 1$ particles accelerate.
- *v_max* — max velocity (usually the width of the optimised function domain) e.g. $domain = \{-5 \dots 5\}$ then $v_max = 10$.
- *max_num_steps* - maxim number of steps e.g. 10000

- A *teminal_condition* control maximum number of steps or finding the solution close to the know global optimum e.g. $f(global_best) - f_globalne < 0,0001$.

- Initialization

Creating a swarm and calculating the local and global best positions.

```

for  $i = 1$  to swarm_size do
    for  $j = 1$  to d do
         $v_{i,j} \leftarrow rand(-v\_max/3, v\_max/3)$ 
         $x_{i,j} \leftarrow rand(domain\_min, domain\_max)$ 
    end for
     $f \leftarrow f(x_i)$ 
     $personal\_best_i \leftarrow x_i$ 
    if  $i == 1$  then
         $global\_best \leftarrow x_i$ 
    end if
    if  $f(personal\_best_i) < f(global\_best)$  then
         $global\_best \leftarrow personal\_best_i$ 
    end if
end for
```

where:

domain_min , *domain_max* min and max value of the optimised function.

- $rU(0, 1)$ — a random number from the uniform distribution from a range [0,1].

3 Benchmarks

To test the algorithm the following function should be used:

1. RASTRIGIN FUNCTION

- <http://www.sfu.ca/~ssurjano/rastr.html>,
- $domain = [-5.12, 5.12]$
- Global minimum $f(0, 0, \dots, 0) = 0$

2. GRIEWANK FUNCTION

- <http://www.sfu.ca/~ssurjano/griewank.html>,
- $domain = [-600, 600]$
- Global minimum $f(0, 0, \dots, 0) = 0$

3. SPHERE FUNCTION

- <http://www.sfu.ca/~ssurjano/spheref.html>,
- $domain = [-5.12, 5.12]$
- Global minimum $f(0, 0, \dots, 0) = 0$

4. ZAKHAROV FUNCTION

- <http://www.sfu.ca/~ssurjano/zakharov.html>,
- $domain = [-5, 10]$
- Global minimum $f(0, 0, \dots, 0) = 0$

5. EASOM FUNCTION

- <http://www.sfu.ca/~ssurjano/easom.html>,
- $domain = [-100, 100]$
- Global minimum $f(\pi, \pi) = -1$

6. STYBLINSKI-TANG FUNCTION

- <http://www.sfu.ca/~ssurjano/stybtang.html>,
- $domain = [-5, 5]$
- Global minimum $f(-2.903534, \dots, -2.903534) = -39.16599d$, where d is dimension